

Two New Examples of TTM

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Abstract

We will review the past history of the attacks and defenses of TTM. The main tool of the past attacks is linear algebra, while the defenses rely on algebraic geometry and commutative algebra. It is hard for attackers to completely succeed against the formidable castle of modern mathematics. It is out of the common sense that problems of algebraic geometry can always be solved by linear algebra. It repeatedly happens that the attackers find some points which could be exploited by linear algebra using complicated computations, usually the attackers overexaggerate the power of linear algebra and illusional believe that they succeed totally, then the points are disappearing by a simple twist in algebraic geometry and commutative algebra. All attacks in the past simply strengthen the structures of TTM. For these facts we are very grateful to the attackers.

Last year there is a paper entitled "Breaking a New Instance of TTM Cryptosystem" by Xuyun Nie, Lei Hu, Jianyu Li, Crystal Updegrove and Jintai Ding [11] claiming a successive attack on the scheme of TTM presented in [7]. In our previous article [8], we show that their claim is a **misunderstanding**.

The discussions of [11] and [8] center on if in [11] the authors really just use the *public keys*. Right after we post [8], to settle the discrepancy of [11] and [8], we have sent the public keys of a new example (which is attached as the **Appendix I** of this article) to the authors of [11] to test their claim in the *abstract* of [11], i.e., they will be able to crack TTM using only the public keys (in 20 minutes as stated in the abstract of [11]). After two weeks, Mr Nie asks the private keys of the new example for his *theoretical analysis* and we will consider his request only if he concedes that he is unable to crack the new example by the method of [11]. Since there is no definite answer from them after 4 months, we will publish the example in this article to give other people chances to attack. Furthermore, we publish a second example as **Appendix II**.

1 Introduction

The TTM cryptosystem (cf [5],[7]) is a truly higher dimensional method. It is given by the composition of *tame* mappings $\pi(= \prod_i \phi_i)$ from K^n to K^m where K is a finite field and $n \leq m$. **The public key is the composition π** (which can be written as a sequence of quadratic polynomials) **while the private key is the set of mappings $\{\phi_i\}$** . The *tame* mappings, which are commonly known in mathematics, are defined as

Definition: We define a *tame* mapping $\phi_i = (\phi_{i,1}, \dots, \phi_{i,m})$ as either a linear transformation, or of the following form in any *order* of variables $x_1, \dots, x_m$ with polynomials $h_{i,j}$,

$$\begin{aligned} (1) : \phi_{i,1}(x_1, \dots, x_m) &= x_1 = y_1 \\ (2) : \phi_{i,2}(x_1, \dots, x_m) &= x_2 + h_{i,2}(x_1) = y_2 \\ &\dots\dots\dots \\ (j) : \phi_{i,j}(x_1, \dots, x_m) &= x_j + h_{i,j}(x_1, \dots, x_{j-1}) = y_j \end{aligned} \tag{1}$$

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$$(m) : \phi_{i,m}(x_1, \dots, x_m) = x_m + h_{i,m}(x_1, \dots, x_{m-1}) = y_m$$

In papers [5],[6], [7], implementations of TTM are given. The public key is the composition of $\phi_4\phi_3\phi_2\phi_1$ which will be written as a sequence of quadratic polynomials. An attacker shall focus on them. The private keys $\phi_4, \phi_3, \phi_2, \phi_1$ are written as polynomials of degrees 1, 8, 2, 1 respectively.

For the users (not the attackers) we provide the decoding process consisting of the private keys which are mainly the inverse linear transformations ϕ_1^{-1}, ϕ_2^{-1} , the *lock polynomials* (which gives ϕ_3^{-1}) and ϕ_4^{-1} .

2 Past History of Attacks and Defenses

The cryptosystem TTM is a method of algebraic geometry and commutative algebra for encryption purpose. It goes through stages of attacks and defenses. We should list some important ones as follows,

(1) Sathaye-Montgomery's attack (private correspondences, 1998): Using linear algebra to analyze the dimension of the vector space generated by the degree 2 forms. As we consider only one *non-linear tame map* at the middle at that time. This method shows that the dimension is $m - 1$, and the whole system can solved successively.

The defense is to increase the number of middle non-linear tame maps to two and invent a lock polynomial for these purpose ([5] 1999). Then the dimension of the vector space generated by the degree 2 forms will be m , and their analysis fails.

(2) Kipnis-Shamir's *relinearization* ([4]) and Courtois-Shamir-Patarin-Klimov's *XL* methods ([1] 2000). The main object of the attacks is Patarin's HFE (*hidden field equation*) which is a 0-dimensional encryption system disguised as multivariate cryptosystem in the tradition of Matsumoto-Imai. The main point of HFE is hiding a field equation (it is 0-dimensional in the sense of algebraic geometry). We show that the said methods applying to TTM, a genuine n -dimensional cryptosystem, are inefficient in [9] (1999) and [10] (2001).

(3) Minrank attack of L.Goubin and N.Courtois ([3], 2000): There they show that we not only have to consider the dimension, but also have to consider the rank to have a secure system. They obtain a formula for complexity, $q^{(rank) \lceil m/n \rceil} \times m^3$ where q is the number of elements in the ground field (which we take to be 2^8). They mistakenly believe that the minrank(as indicated by (*rank*) in the preceding formula) of TTM is always 2 (otherwise their attack will fail).

The defense is to increase the number of lock polynomials to at least four, and the minrank to 4 or more, thus the minrank attack fail ([6] 2001).

(4) The generalized Patarin attack of Ding-Schmidt([2] 2003): Their attack is using the linear equations produced by the generalized Patarin attack as finding coefficients $a, \{b_i\}, \{c_j\}, \{d_{ij}\}$ in the following formula,

$$a + \sum_i b_i x_i + \sum_j c_j y_j + \sum_{i,j} d_{ij} x_i y_j = 0$$

As long as the number of free variables is tolerably small (say, < 9), then all free variables may be assigned to all possible values in the finite field (say, $GL(2^8)$) to find the right system of linear equations, thus the whole system can be solved.

The defense is to slightly modify the system so that the number of free variables is intolerably high (say, > 10) ([7] 2004) and the attack of Ding-Schmidt fails.

(5) Rely on the knowledge of the private key and the process of constructing the private key (i.e., knowing the compact forms of the lock polynomials), Xuyun Nie-Lei Hu-Jianyu Li-Crystal Updegrove-Jintai Ding ([11] 2006) show that they may use the following criterion to find the values of $\{b_{kj}\}, \{c_i\}$

satisfying the following inequality and solve the system step by step,

$$\text{degree}(\sum b_{jk}y_jy_k + \sum c_iy_i) \leq 1 \text{ or } 2$$

The defense is to make the above equations simply producing constant or *parasite* (i.e., useless) polynomials (**Appendix I** of this article, they are sent to the authors of [11] in 2006). The reader is referred to the next two sections to see the details

3 Legitimate Attack

The strength of a public key system is solely on the public key, i.e., with the public key known to the general public, the attacker tries to find the private key or its equivalences. Note that the attacker has no information about the private key nor how it is constructed. By the constructions of the private keys, we mean the **compact** expressions of the lock polynomials.

The attacker on TTM shall only use the public key which is a sequence of quadratic polynomials. The so called *lock polynomials* are parts of ϕ_3 , hence are parts of the *private keys*. In the *abstract* of article [11], the authors claim that they only use the public key, while in the *content* of article [11], they use the private keys and their constructions (i.e., their compact forms) freely. It will be unfair to them to ask them to completely forget the *lock polynomials* and the *constructions* (i.e., their compact forms) of the *lock polynomials* of the example in [7]. The only fair way is to provide them with another example so they may test their skill.

Right after we post our article [8], we have sent Mr Nie and Dr Ding the public keys of our example in the **Appendix I** of this article for Mr Nie to fulfill his claim that he will crack our examples in two weeks. BTW, they claim that the complexity of our system is 2^{38} which can be translated to less than 20 minutes on a PC of 256 Hz. How does he explain that he needs two weeks? After two weeks, he has sent us a surprising email: "... Hence, for theoretical analysis, one should assume that the adversary (attacker) know the explicit forms of central map (lock polynomials)." (on 5 Jan 2007). This is absurd! The central polynomials (lock polynomials) are part of the private key. Apparently, they are confused about what are public keys and what are private keys. We feel that to provide the *lock polynomials* will not help the *theoretical analysis* of our system. The hard parts are the constructions (i.e., their compact forms) of the *lock polynomials*. It is easy to see that there are vast number of ways to construct the *lock polynomials*. It is impossible to guess right the construction (i.e., their compact forms). The constructions (i.e., their compact forms) are even routinely hidden from the legitimate users. He has to request both the *lock polynomials* and the *constructions* (i.e., their compact forms) of them. However, to keep the contest pure and to test their claim in the *abstract* of [11], we refuse to give him the parts of the private keys unconditionally.

4 On the Appendix

Instead of publishing the composition of $\phi_4\phi_3\phi_2\phi_1$ which will be written as a sequence of long quadratic polynomials, we publish the explicit forms of $\phi_3\phi_2$. The polynomials $\{fi\}$ in **Appendix I** are general quadratic polynomials in $x_0, \dots, x_{i-1}$. The honest attacker should assign explicit forms to $\{fi\}$ and add general linear transformations ϕ_4, ϕ_1 on both sides of $\phi_3\phi_2$.

We will be refrained from comment on **Appendix I**. As for **Appendix II**, we have

- (1) Knowing the lock polynomials, the method of [11] will produce
a security of 2^{138} .
- (2) Knowing the lock polynomials and the constructing process (i.e., their compact forms),

the method of [11] will produce a security of 2^{109} .

The above shows that the example of **Appendix II** is even secured from the inventor using the method of [11].

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Appendix I

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y0 := x4 x3 + x1 x2 + x0
y1 := x55 x60 + x51 x61 + x50 x62 + x54 x63 + x1
y2 := x71 x76 + x67 x77 + x66 x78 + x70 x79 + x2
y3 := x87 x92 + x83 x93 + x82 x94 + x86 x95 + x3
y4 := x39 x44 + x35 x45 + x34 x46 + x38 x47 + x4
y5 := f5 + x5
y6 := f6 + x6
y7 := f7 + x7
y8 := f8 + x8
y9 := f9 + x9
y10 := f10 + x10
y11 := x4 x5 + x1 x0 + x8 + x11
y12 := f12 + x12
y13 := f13 + x13
y14 := f14 + x14
y15 := f15 + x15
y16 := f16 + x5
y17 := f17 + x6
y18 := f18 + x7
y19 := x4 x17 + x2 x15 + x19
y20 := x1 x17 + x2 x16 + x20
y21 := x14 x5 + x13 x7 + x21
y22 := x14 x0 + x12 x7 + x22
y23 := f23 + x23
y24 := x12 x5 + x13 x0 + x24 + x11
y25 := f25 + x25
y26 := f26 + x26
y27 := x12 x16 + x13 x15 + x24 + x27
y28 := x12 x17 + x18 x15 + x28
y29 := x13 x17 + x18 x16 + x29
y30 := x14 x16 + x13 x23 + x30
y31 := x14 x15 + x12 x23 + x31
y32 := f32 + x32
y33 := f33 + x33
y34 := f34 + x34
y35 := f35 + x35
y36 := f36 + x36
y37 := f37 + x37
y38 := f38 + x38
y39 := f39 + x39
y40 := f40 + x40
y41 := f41 + x41
y42 := f42 + x42
y43 := x32 x37 + x33 x36 + x40 + x43
y44 := x32 x38 + x34 x36 + x44
y45 := x33 x38 + x34 x37 + x45
y46 := x35 x37 + x33 x39 + x46
y47 := x35 x36 + x32 x39 + x47
y48 := f48 + x48
y49 := f49 + x49
y50 := f50 + x50
y51 := f51 + x51
y52 := f52 + x52
y53 := f53 + x53
y54 := f54 + x54
y55 := f55 + x55
y56 := f56 + x56
y57 := f57 + x57
y58 := f58 + x58
y59 := x48 x53 + x49 x52 + x56 + x59
y60 := x48 x54 + x50 x52 + x60
y61 := x49 x54 + x50 x53 + x61
y62 := x51 x53 + x49 x55 + x62
y63 := x51 x52 + x48 x55 + x63
y64 := f64 + x64
y65 := f65 + x65
y66 := f66 + x66
y67 := f67 + x67
y68 := f68 + x68
y69 := f69 + x69
y70 := f70 + x70
y71 := f71 + x71
y72 := f72 + x72
y73 := f73 + x73
y74 := f74 + x74
y75 := x64 x69 + x65 x68 + x72 + x75
y76 := x64 x70 + x66 x68 + x76
y77 := x65 x70 + x66 x69 + x77
y78 := x67 x69 + x65 x71 + x78
y79 := x67 x68 + x64 x71 + x79
y80 := f80 + x80
y81 := f81 + x81
y82 := f82 + x82
y83 := f83 + x83
y84 := f84 + x84
y85 := f85 + x85
y86 := f86 + x86
y87 := f87 + x87
y88 := f88 + x88
y89 := f89 + x89
y90 := f90 + x90
y91 := x80 x85 + x81 x84 + x88 + x91
y92 := x80 x86 + x82 x84 + x92
y93 := x81 x86 + x82 x85 + x93
y94 := x83 x85 + x81 x87 + x94
y95 := x83 x84 + x80 x87 + x95
y96 := f96 + x96
y97 := f97 + x97
y98 := f98 + x98
y99 := f99 + x99
y100 := f100 + x100
y101 := f101 + x101
y102 := f102 + x102
y103 := x4 x6 + x0 x30 + x14
y104 := x1 x6 + x30 x5 + x10
y105 := x23 x5 + x1 x7 + x21
y106 := x0 x23 + x4 x7 + x22
y107 := x4 x16 + x1 x15 + x8 + x27
y108 := x3 x16 + x1 x23 + x30
y109 := x3 x15 + x23 x4 + x31
y110 := x12 x6 + x18 x0 + x28
y111 := x13 x6 + x18 x5 + x29
y112 := x20 x17 + x19 x18 + x2 + x29
y113 := x20 x23 + x8 x18 + x1
y114 := x19 x23 + x8 x17 + x4
y115 := x10 x17 + x19 x14 + x30
y116 := x10 x18 + x20 x14 + x31
y117 := x4 x20 + x1 x19 + x2 x8 + x3 x10
y118 := x0 x21 + x5 x22 + x6 x9 + x7 x11
y119 := x10 x0 + x14 x5 + x6 x8 + x7 x31
y120 := x4 x21 + x1 x22 + x30 x9 + x23 x11
y121 := x10 x22 + x14 x21
y122 := x10 x9 + x8 x21 + x7
y123 := x14 x9 + x8 x22 + x23
y124 := x31 x22 + x14 x11 + x30
y125 := x31 x9 + x8 x11 + x1 + x0
y126 := x23 x6 + x30 x7
y127 := x31 x21 + x10 x11 + x6
y128 := x15 x29 + x16 x28 + x17 x24 + x23 x26
y129 := x12 x30 + x13 x31 + x18 x25 + x14 x27
y130 := x29 x31 + x28 x30

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$y_{131} := x_{29} x_{25} + x_{24} x_{30} + x_{23}$
 $y_{132} := x_{28} x_{25} + x_{24} x_{31} + x_{14}$
 $y_{133} := x_{26} x_{31} + x_{28} x_{27} + x_{18}$
 $y_{134} := x_{26} x_{25} + x_{24} x_{27} + x_{13} + x_{15}$
 $y_{135} := x_{14} x_{17} + x_{18} x_{23}$
 $y_{136} := x_{26} x_{30} + x_{29} x_{27} + x_{17}$
 $y_{137} := x_{15} x_{20} + x_{16} x_{19} + x_8 x_{17} + x_{23} x_{10}$
 $y_{138} := x_{30} x_4 + x_1 x_{31} + x_2 x_{25} + x_3 x_{27}$
 $y_{139} := x_{20} x_{31} + x_{19} x_{30}$
 $y_{140} := x_{20} x_{25} + x_8 x_{30} + x_{23}$
 $y_{141} := x_{19} x_{25} + x_8 x_{31} + x_3$
 $y_{142} := x_{10} x_{31} + x_{19} x_{27} + x_2$
 $y_{143} := x_{10} x_{25} + x_8 x_{27} + x_1 + x_{15}$
 $y_{144} := x_3 x_{17} + x_2 x_{23}$
 $y_{145} := x_{10} x_{30} + x_{20} x_{27} + x_{17}$
 $y_{146} := x_{19} x_{23} + x_3 x_{20} + x_2 x_{30} + x_{17} x_{31}$
 $y_{147} := x_{28} x_7 + x_{14} x_{29} + x_{18} x_{21} + x_6 x_{22}$
 $y_{148} := x_0 x_{29} + x_5 x_{28} + x_6 x_{24} + x_7 x_{26}$
 $y_{149} := x_{12} x_{21} + x_{13} x_{22} + x_{18} x_9 + x_{14} x_{11}$
 $y_{150} := x_{29} x_{22} + x_{28} x_{21}$
 $y_{151} := x_{29} x_9 + x_{24} x_{21} + x_7$
 $y_{152} := x_{28} x_9 + x_{24} x_{22} + x_{14}$
 $y_{153} := x_{26} x_{22} + x_{28} x_{11} + x_{18}$
 $y_{154} := x_{26} x_9 + x_{24} x_{11} + x_{13} + x_0$
 $y_{155} := x_{14} x_6 + x_{18} x_7$
 $y_{156} := x_{26} x_{21} + x_{29} x_{11} + x_6$
 $y_{157} := x_{18} x_4 + x_1 x_{17} + x_2 x_{23} + x_{14} x_3$
 $y_{158} := x_{20} x_{30} + x_{19} x_{31} + x_8 x_{28} + x_{10} x_{29}$
 $y_{159} := x_4 x_{31} + x_1 x_{30}$
 $y_{160} := x_4 x_{28} + x_2 x_{30} + x_{14}$
 $y_{161} := x_1 x_{28} + x_2 x_{31} + x_{10}$
 $y_{162} := x_3 x_{31} + x_1 x_{29} + x_8$
 $y_{163} := x_3 x_{28} + x_2 x_{29} + x_{19} + x_{18}$
 $y_{164} := x_{23} x_{10} + x_8 x_{14}$
 $y_{165} := x_3 x_{30} + x_4 x_{29} + x_{23}$
 $y_{166} := x_{14} x_7 + x_{23} x_{10} + x_{30} x_{21} + x_6 x_{22}$
 $+ x_{32} x_{45} + x_{33} x_{44} + x_{34} x_{40} + x_{35} x_{42}$
 $y_{167} := x_{14} x_7 + x_{23} x_{10} + x_{30} x_{21} + x_6 x_{22}$
 $+ x_{36} x_{46} + x_{37} x_{47} + x_{38} x_{41} + x_{39} x_{43}$
 $y_{168} := x_{36} x_{45} + x_{37} x_{44} + x_{38} x_{40} + x_{39} x_{42}$
 $y_{169} := x_{32} x_{46} + x_{33} x_{47} + x_{34} x_{41} + x_{35} x_{43}$
 $y_{170} := x_{45} x_{47} + x_{44} x_{46}$
 $y_{171} := x_{45} x_{41} + x_{40} x_{46} + x_{39}$
 $y_{172} := x_{44} x_{41} + x_{40} x_{47} + x_{35}$
 $y_{173} := x_{42} x_{47} + x_{44} x_{43} + x_{34}$
 $y_{174} := x_{42} x_{41} + x_{40} x_{43} + x_{33} + x_{36}$
 $y_{175} := x_{35} x_{38} + x_{34} x_{39}$
 $y_{176} := x_{42} x_{46} + x_{45} x_{43} + x_{38}$
 $y_{177} := x_{14} x_7 + x_{23} x_{10} + x_{30} x_{21} + x_6 x_{22}$
 $+ x_{48} x_{61} + x_{49} x_{60} + x_{50} x_{56} + x_{51} x_{58}$
 $y_{178} := x_{14} x_7 + x_{23} x_{10} + x_{30} x_{21} + x_6 x_{22}$
 $+ x_{52} x_{62} + x_{53} x_{63} + x_{54} x_{57} + x_{55} x_{59}$
 $y_{179} := x_{52} x_{61} + x_{53} x_{60} + x_{54} x_{56} + x_{55} x_{58}$
 $y_{180} := x_{48} x_{62} + x_{49} x_{63} + x_{50} x_{57} + x_{51} x_{59}$
 $y_{181} := x_{61} x_{63} + x_{60} x_{62}$
 $y_{182} := x_{61} x_{57} + x_{56} x_{62} + x_{55}$
 $y_{183} := x_{60} x_{57} + x_{56} x_{63} + x_{51}$
 $y_{184} := x_{58} x_{63} + x_{60} x_{59} + x_{50}$
 $y_{185} := x_{58} x_{57} + x_{56} x_{59} + x_{49} + x_{52}$
 $y_{186} := x_{51} x_{54} + x_{50} x_{55}$
 $y_{187} := x_{58} x_{62} + x_{61} x_{59} + x_{54}$
 $y_{188} := x_{14} x_7 + x_{23} x_{10} + x_{30} x_{21} + x_6 x_{22}$
 $+ x_{64} x_{77} + x_{65} x_{76} + x_{66} x_{72} + x_{67} x_{74}$
 $y_{189} := x_{14} x_7 + x_{23} x_{10} + x_{30} x_{21} + x_6 x_{22}$
 $+ x_{68} x_{78} + x_{69} x_{79} + x_{70} x_{73} + x_{71} x_{75}$
 $y_{190} := x_{68} x_{77} + x_{69} x_{76} + x_{70} x_{72} + x_{71} x_{74}$
 $y_{191} := x_{64} x_{78} + x_{65} x_{79} + x_{66} x_{73} + x_{67} x_{75}$
 $y_{192} := x_{77} x_{79} + x_{76} x_{78}$
 $y_{193} := x_{77} x_{73} + x_{72} x_{78} + x_{71}$
 $y_{194} := x_{76} x_{73} + x_{72} x_{79} + x_{67}$
 $y_{195} := x_{74} x_{79} + x_{76} x_{75} + x_{66}$
 $y_{196} := x_{74} x_{73} + x_{72} x_{75} + x_{65} + x_{68}$
 $y_{197} := x_{67} x_{70} + x_{66} x_{71}$
 $y_{198} := x_{74} x_{78} + x_{77} x_{75} + x_{70}$
 $y_{199} := x_{14} x_7 + x_{23} x_{10} + x_{30} x_{21} + x_6 x_{22}$
 $+ x_{80} x_{93} + x_{81} x_{92} + x_{82} x_{88} + x_{83} x_{90}$
 $y_{200} := x_{14} x_7 + x_{23} x_{10} + x_{30} x_{21} + x_6 x_{22}$
 $+ x_{84} x_{94} + x_{85} x_{95} + x_{86} x_{89} + x_{87} x_{91}$
 $y_{201} := x_{84} x_{93} + x_{85} x_{92} + x_{86} x_{88} + x_{87} x_{90}$
 $y_{202} := x_{80} x_{94} + x_{81} x_{95} + x_{82} x_{89} + x_{83} x_{91}$
 $y_{203} := x_{93} x_{95} + x_{92} x_{94}$
 $y_{204} := x_{93} x_{89} + x_{88} x_{94} + x_{87}$
 $y_{205} := x_{92} x_{89} + x_{88} x_{95} + x_{83}$
 $y_{206} := x_{90} x_{95} + x_{92} x_{91} + x_{82}$
 $y_{207} := x_{90} x_{89} + x_{88} x_{91} + x_{81} + x_{84}$
 $y_{208} := x_{83} x_{86} + x_{82} x_{87}$
 $y_{209} := x_{90} x_{94} + x_{93} x_{91} + x_{86}$

Appendix II

$y_0 := x_1 x_4 + x_2 x_3 + x_0$
 $y_1 := x_{96} x_{100} + x_{92} x_{102} + x_{91} x_{103} + x_{95} x_{104} + x_1$
 $y_2 := x_{80} x_{85} + x_{76} x_{86} + x_{75} x_{87} + x_{79} x_{88} + x_2$
 $y_3 := x_{64} x_{69} + x_{60} x_{70} + x_{59} x_{71} + x_{63} x_{72} + x_1 x_2 + x_3$
 $y_4 := x_{48} x_{53} + x_{44} x_{54} + x_{43} x_{55} + x_{47} x_{56} + x_1 x_3 + x_2 x_3 + x_4$
 $y_5 := x_0 x_4 + x_1 x_2 + x_3 x_4 + x_2 x_4 + x_2 x_3 + x_1 x_3 + x_5$
 $y_6 := x_5 x_0 + x_1 x_4 + x_2 x_3 + x_5 x_1 + x_2 x_4 + x_6$
 $y_7 := x_6 x_0 + x_5 x_1 + x_3 x_4 + x_2 x_6 + x_5 x_4 + x_7$
 $y_8 := x_7 x_1 + x_2 x_6 + x_5 x_3 + x_4 x_7 + x_3 x_6 + x_8$
 $y_9 := x_8 x_0 + x_7 x_2 + x_6 x_4 + x_5 x_1 + x_4 x_7 + x_9$
 $y_{10} := x_9 x_0 + x_8 x_1 + x_7 x_2 + x_3 x_6 + x_5 x_4 + x_{10}$
 $y_{11} := x_6 x_{10} + x_7 x_9 + x_6 + x_9 + x_{10} + x_{11}$
 $y_{12} := x_5 x_{10} + x_7 x_8 + x_5 + x_8 + x_{10} + x_{12}$
 $y_{13} := x_5 x_9 + x_8 x_6 + x_8 + x_9 + x_{13}$
 $y_{14} := x_{13} x_8 + x_{12} x_9 + x_{11} x_{10} + x_{13} x_{11} + x_{12} x_7 + x_{14}$
 $y_{15} := x_{14} x_4 + x_{13} x_5 + x_{12} x_6 + x_{11} x_7 + x_{10} x_8 + x_{15}$
 $y_{16} := x_{15} x_{14} + x_{13} x_{12} + x_{11} x_{10} + x_9 x_8 + x_7 x_6 + x_{16}$
 $y_{17} := x_{16} x_{15} + x_{14} x_5 + x_{13} x_6 + x_{12} x_7 + x_{11} x_8 + x_{17}$
 $y_{18} := x_{17} x_5 + x_{16} x_{10} + x_{15} x_{11} + x_{14} x_{12} + x_{13} x_6 + x_{18}$
 $y_{19} := x_{18} x_4 + x_{17} x_6 + x_{16} x_8 + x_{15} x_{10} + x_{14} x_{12} + x_{19}$
 $y_{20} := x_{19} x_7 + x_{18} x_9 + x_{17} x_{11} + x_{16} x_{13} + x_{15} x_8 + x_{20}$
 $y_{21} := x_{20} x_{16} + x_{19} x_{14} x_{18} x_{12} + x_{17} x_{10} + x_{16} x_8 + x_{21}$
 $y_{22} := x_{21} x_8 + x_{20} x_9 + x_{19} x_{10} + x_{18} x_{11} + x_{17} x_{12} + x_{22}$
 $y_{23} := x_{18} x_{22} + x_{19} x_{21} + x_{18} + x_{21} + x_{22} + x_{23}$
 $y_{24} := x_{17} x_{22} + x_{19} x_{20} + x_{17} + x_{20} + x_{22} + x_{24}$
 $y_{25} := x_{17} x_{21} + x_{20} x_{18} + x_{20} + x_{21} + x_{25}$
 $y_{26} := x_{25} x_{11} + x_{24} x_{12} + x_{23} x_{13} + x_{22} x_{14} + x_{26}$
 $y_{27} := x_{26} x_5 + x_{25} x_7 + x_{24} x_9 + x_{23} x_{11} + x_{22} x_{13} + x_{27}$
 $y_{28} := x_{27} x_6 + x_{26} x_8 + x_{25} x_{10} + x_{24} x_{12} + x_{23} x_{14} + x_{28} + x_{27} + x_{26}$
 $y_{29} := x_{28} x_5 + x_{27} x_7 + x_{26} x_9 + x_{25} x_{11} + x_{24} x_{13} + x_{29} + x_{21} + x_{22}$
 $y_{30} := x_{29} x_{15} + x_{28} x_{16} + x_{27} x_{17} + x_{26} x_{18} + x_{25} x_{19} + x_{24} x_{18} + x_{30}$
 $y_{31} := x_{30} x_{17} + x_{28} x_{18} + x_{26} x_{19} + x_{24} x_{20} + x_{22} x_{21} + x_{23} x_6 + x_{31} + x_{30} + x_{29}$
 $y_{32} := x_{31} x_7 + x_{30} x_8 + x_{29} x_9 + x_{28} x_{10} + x_{27} x_{11} + x_{26} x_{12} + x_{25} x_{13} + x_{32} + x_{27} + x_{23}$
 $y_{33} := x_{32} x_5 + x_{31} x_6 + x_{30} x_7 + x_{29} x_{14} + x_{28} x_{15} + x_{27} x_{16} + x_{26} x_{17} + x_{33} + x_5 + x_6$
 $y_{34} := x_{33} x_{20} + x_{32} x_{19} + x_{31} x_{18} + x_{30} x_{17} + x_{29} x_{16} + x_{28} x_{15} + x_{34} + x_4 + x_{10} + x_{11}$
 $y_{35} := x_{30} x_{22} + x_{31} x_{21} + x_{30} + x_{21} + x_{22} + x_{35}$
 $y_{36} := x_{29} x_{22} + x_{31} x_{20} + x_{29} + x_{20} + x_{22} + x_{36}$
 $y_{37} := x_{29} x_{21} + x_{20} x_{30} + x_{20} + x_{21} + x_{37}$
 $y_{38} := x_{33} x_7 + x_{34} x_6 + x_6 + x_{33} + x_{34} + x_{38}$
 $y_{39} := x_{32} x_7 + x_{34} x_5 + x_5 + x_{32} + x_{34} + x_{39}$
 $y_{40} := x_{32} x_6 + x_5 x_{33} + x_{32} + x_{33} + x_{40}$
 $y_{41} := x_{40} x_1 + x_{39} x_3 + x_{38} x_5 + x_{37} x_7 + x_{36} x_9 + x_{35} x_{11} + x_{41} + x_{40} + x_{39}$
 $y_{42} := x_{41} x_2 + x_{40} x_4 + x_{39} x_6 + x_{38} x_8 + x_{37} x_{10}$

$+ x_{36} x_{12} + x_{42} + x_{38} + x_{37}$
 $y_{43} := x_{42} x_{13} x_{41} x_{15} + x_{40} x_{17} + x_{39} x_{19} + x_{38} x_{21} + x_{37} x_{23} + x_{43}$
 $y_{44} := x_{43} x_{14} + x_{42} x_{26} + x_{41} x_{18} + x_{40} x_{20} + x_{39} x_{22} + x_{38} x_{24} + x_{44} + x_{43} + x_3$
 $y_{45} := x_{44} x_{25} + x_{43} x_{27} + x_{42} x_{29} + x_{41} x_{31} + x_{40} x_{33} + x_{39} x_{35} + x_{45} + x_8 + x_6$
 $y_{46} := x_{45} x_{26} + x_{44} x_{28} + x_{43} x_{30} + x_{42} x_{32} + x_{41} x_{34} + x_{40} x_{36} + x_{46} + x_{40} + x_{39}$
 $y_{47} := x_{46} x_1 x_{45} x_4 + x_{44} x_7 + x_{43} x_{10} + x_{42} x_{13} + x_{41} x_{16} + x_{40} x_{19} + x_{47} + x_3 + x_7$
 $y_{48} := x_{47} x_2 + x_{46} x_5 + x_{45} x_8 + x_{44} x_{11} + x_{43} x_{14} + x_{42} x_{17} + x_{41} x_{20} + x_{48} + x_{47} + x_{38}$
 $y_{49} := x_{48} x_3 + x_{47} x_6 + x_{46} x_9 + x_{45} x_{12} + x_{44} x_{15} + x_{43} x_{18} + x_{42} x_{21} + x_{49}$
 $y_{50} := x_{49} x_{22} + x_{48} x_{25} + x_{47} x_{28} + x_{46} x_{31} + x_{45} x_{34} + x_{44} x_{37} + x_{43} x_{40} + x_{50} + x_{10} + x_{17}$
 $y_{51} := x_{50} x_{23} + x_{49} x_{26} + x_{48} x_{29} + x_{47} x_{32} + x_{46} x_{35} + x_{45} x_{38} + x_{44} x_{41} + x_{51} + x_8 + x_{22}$
 $y_{52} := x_{41} x_{46} + x_{42} x_{45} + x_{49} + x_{52}$
 $y_{53} := x_{41} x_{47} + x_{43} x_{45} + x_{53}$
 $y_{54} := x_{42} x_{47} + x_{43} x_{46} + x_{54}$
 $y_{55} := x_{44} x_{46} + x_{42} x_{48} + x_{55}$
 $y_{56} := x_{44} x_{45} + x_{41} x_{48} + x_{56}$
 $y_{57} := x_{56} x_0 + x_{55} x_5 + x_{54} x_{10} + x_{53} x_{15} + x_{52} x_{20} + x_{51} x_{25} + x_{50} x_{30} + x_{57} + x_{56}$
 $y_{58} := x_{57} x_1 + x_{56} x_6 + x_{55} x_{11} + x_{54} x_{16} + x_{53} x_{21} + x_{52} x_{26} + x_{51} x_{31} + x_{58} + x_{52} + x_{47}$
 $y_{59} := x_{55} x_2 + x_{54} x_7 + x_{53} x_{12} + x_{52} x_{17} + x_{51} x_{22} + x_{50} x_{27} + x_{49} x_{32} + x_{59} + x_{20} + x_{15}$
 $y_{60} := x_{59} x_3 + x_{58} x_8 + x_{57} x_{13} + x_{56} x_{18} + x_{55} x_{23} + x_{54} x_{28} + x_{53} x_{13} + x_{60} + x_2 + x_8$
 $y_{61} := x_{56} x_7 + x_{44} x_8 + x_{33} x_{17} + x_{35} x_{20} + x_{40} x_{22} + x_{48} x_{25} + x_{23} x_{24} + x_{60} + x_7 + x_{15}$
 $y_{62} := x_{61} x_{20} + x_{37} x_{38} + x_{44} x_{34} + x_{57} x_9 + x_{59} x_{15} + x_{40} x_{39} + x_{60} x_2 + x_{62} + x_9 + x_{35}$
 $y_{63} := x_{62} x_{15} + x_{58} x_7 + x_{37} x_{13} + x_{48} x_{16} + x_{36} x_{38} + x_{27} x_{44} + x_{55} x_3 + x_{63} + x_{44}$
 $y_{64} := x_{61} x_{19} + x_{60} x_9 + x_{54} x_{17} + x_{41} x_{52} + x_{56} x_{28} + x_3 x_6 + x_{16} x_8 + x_{64} + x_{23} + x_{17}$
 $y_{65} := x_{64} x_{63} + x_{34} x_{56} + x_{29} x_{41} + x_{31} x_{61} + x_{55} x_{37} + x_{59} x_{62} + x_1 x_{56} + x_{65} + x_6$
 $y_{66} := x_{65} x_{64} + x_1 x_{27} + x_{47} x_{59} + x_{38} x_{39} + x_{48} x_{50} + x_{27} x_{62} + x_{36} x_{57} + x_{66} + x_{56} + x_{46}$
 $y_{67} := x_{65} x_{63} + x_{38} x_{58} + x_{27} x_{39} + x_{37} x_{59} + x_{40} x_{65} + x_4 x_{34} + x_{15} x_{46} + x_{67} + x_4 + x_{16}$
 $y_{68} := x_{57} x_{62} + x_{58} x_{61} + x_{65} + x_{68}$
 $y_{69} := x_{57} x_{63} + x_{59} x_{61} + x_{69}$
 $y_{70} := x_{58} x_{63} + x_{59} x_{62} + x_{70}$
 $y_{71} := x_{60} x_{62} + x_{58} x_{64} + x_{71}$
 $y_{72} := x_{60} x_{61} + x_{57} x_{64} + x_{72}$
 $y_{73} := x_{72} x_{71} + x_{70} x_{69} + x_{68} x_{67} + x_1 x_{19} + x_{25} x_{70} + x_{36} x_{68} + x_{57} x_{66} + x_{73} + x_{72} + x_9$
 $y_{74} := x_{73} x_5 + x_{72} x_9 + x_{71} x_{15} + x_{68} x_3 + x_{69} x_{27} + x_{38} x_{49} + x_{40} x_{70} + x_{74} + x_{11} + x_{21}$
 $y_{75} := x_{74} x_4 + x_{72} x_{67} + x_{36} x_{68} + x_{49} x_{51} + x_{27} x_{67} + x_{39} x_{44} + x_{48} x_{66} + x_{75} + x_{12} + x_{22}$
 $y_{76} := x_{74} x_{75} + x_{49} x_{27} + x_{36} x_1 + x_{46} x_{65} + x_{70} x_6 + x_{71} x_{18} + x_{72} x_7 + x_{76} + x_{13} + x_{34}$
 $y_{77} := x_{76} x_0 + x_{75} x_{16} + x_{68} x_{24} + x_{74} x_{69} + x_{73} x_{57} + x_{70} x_{27} + x_{69} x_{17} + x_{77} + x_{18} + x_{29}$
 $y_{78} := x_{77} x_9 + x_{76} x_{30} + x_{75} x_{73} + x_{74} x_{41} + x_{73} x_{45} + x_{68} x_{53} + x_{69} x_{62} + x_{78} + x_{12} + x_{37}$
 $y_{79} := x_{78} x_{41} + x_{77} x_{31} + x_{76} x_7 + x_{67} x_{75} + x_{39} x_{51} + x_{45} x_{63} + x_{29} x_{28} + x_{79} + x_0 + x_{27} + x_{49}$

$y_{80} := x_{79} x_{71} + x_{74} x_{75} + x_{76} x_{77} + x_{38} x_{47}$
 $+ x_{45} x_{62} + x_{37} x_{71} + x_{25} x_{53} + x_{80} + x_{71} + x_{47}$
 $y_{81} := x_{80} x_{72} + x_{79} x_{78} + x_{48} x_{64} + x_{78} x_5$
 $+ x_{77} x_9 + x_{71} x_{36} + x_{68} x_{59} + x_{81} + x_{80} + x_{35}$
 $y_{82} := x_{81} x_{49} + x_{79} x_{26} + x_{77} x_{10} + x_{75} x_{47}$
 $+ x_{73} x_{64} + x_{71} x_{70} + x_{79} x_3 + x_{82} + x_{56} + x_{49}$
 $y_{83} := x_{82} x_8 + x_{73} x_{74} + x_{81} x_{69} + x_{79} x_{78}$
 $+ x_{35} x_{61} + x_{74} x_{75} + x_{80} x_{72} + x_{83} + x_1 + x_{48}$
 $y_{84} := x_{73} x_{78} + x_{74} x_{77} + x_{81} + x_{84}$
 $y_{85} := x_{73} x_{79} + x_{75} x_{77} + x_{85}$
 $y_{86} := x_{74} x_{79} + x_{75} x_{78} + x_{86}$
 $y_{87} := x_{76} x_{78} + x_{74} x_{80} + x_{87}$
 $y_{88} := x_{76} x_{77} + x_{73} x_{80} + x_{88}$
 $y_{89} := x_{88} x_{84} + x_{87} x_{10} + x_{86} x_{29} + x_{85} x_{21}$
 $+ x_{83} x_{19} + x_{79} x_{14} + x_{78} x_{65} + x_{89} + x_{84} + x_{11}$
 $y_{90} := x_{89} x_{11} + x_{35} x_{77} + x_{83} x_{87} + x_{84} x_{27}$
 $+ x_{85} x_{37} + x_{86} x_{47} + x_{88} x_{57} + x_{90} + x_{85} + x_4$
 $y_{91} := x_{90} x_6 + x_{88} x_{15} + x_{87} x_{23} + x_{86} x_{35}$
 $+ x_{85} x_{84} + x_{83} x_{17} + x_{79} x_{34} + x_{91} + x_{88} + x_{43}$
 $y_{92} := x_{91} x_{12} + x_{89} x_{13} + x_{90} x_{14} + x_{88} x_{21}$
 $+ x_{87} x_{31} + x_{86} x_{41} + x_{67} x_{65} + x_{92} + x_{87} + x_{21}$
 $y_{93} := x_{92} x_{24} + x_{90} x_{56} + x_{88} x_{63} + x_{86} x_{54}$
 $+ x_{84} x_{44} + x_{79} x_{56} + x_{78} x_{91} + x_{93} + x_{89} + x_{42}$
 $y_{94} := x_{93} x_{17} + x_{86} x_{26} + x_{92} x_{35} + x_{91} x_{90}$
 $+ x_{89} x_{44} + x_{88} x_{51} + x_{87} x_{66} + x_{94} + x_{78} + x_3$
 $+ x_{17}$
 $y_{95} := x_{94} x_{11} + x_{93} x_1 + x_{92} x_{41} + x_{91} x_{55}$
 $+ x_{89} x_{33} + x_{88} x_{71} + x_{87} x_{22} + x_{95} + x_1 + x_{17}$
 $+ x_{29}$
 $y_{96} := x_{95} x_4 + x_{94} x_{17} + x_{93} x_{29} + x_{92} x_{77}$
 $+ x_{91} x_{76} + x_{90} x_{53} + x_{89} x_{65} + x_{96} + x_{94} + x_{19}$
 $y_{97} := x_{96} x_5 + x_{94} x_{53} + x_{94} x_{16} + x_{92} x_{88}$
 $+ x_{91} x_{75} + x_{90} x_{62} + x_{89} x_{77} + x_{97} + x_7 + x_{18}$
 $y_{98} := x_{97} x_8 + x_{96} x_{17} + x_{95} x_{89} + x_{92} x_{73}$
 $+ x_{81} x_{82} + x_{90} x_{82} + x_{89} x_{84} + x_{98} + x_9 + x_{27}$
 $y_{99} := x_{98} x_7 + x_{96} x_{97} + x_{95} x_{23} + x_{92} x_{71}$
 $+ x_{81} x_{90} + x_{82} x_{89} + x_{85} x_{86} + x_{99} + x_{89} + x_{12}$
 $y_{100} := x_{95} x_{89} + x_{91} x_{93} + x_{100}$
 $y_{101} := x_{89} x_{94} + x_{90} x_{93} + x_{97} + x_{101}$
 $y_{102} := x_{90} x_{95} + x_{91} x_{94} + x_{102}$
 $y_{103} := x_{92} x_{94} + x_{90} x_{96} + x_{103}$
 $y_{104} := x_{92} x_{93} + x_{89} x_{96} + x_{104}$
 $y_{105} := x_1 x_{34} + x_2 x_{33} + x_1 + x_{33} + x_{34} + x_{105}$
 $y_{106} := x_0 x_{34} + x_2 x_{32} + x_0 + x_{32} + x_{34} + x_{106}$
 $y_{107} := x_0 x_{33} + x_{32} x_1 + x_{32} + x_{33} + x_{107}$
 $y_{109} := x_4 x_{19} + x_{108} x_{18} + x_4 + x_{108} + x_{18}$
 $+ 1 + x_{19} + x_{109}$
 $y_{110} := x_3 x_{19} + x_{108} x_{17} + x_3 + x_{108} + x_{17}$
 $+ 1 + x_{19} + x_{110}$
 $y_{111} := x_3 x_{18} + x_{17} x_4 + x_3 + x_4 + x_{17} + x_{18}$
 $+ x_{111}$
 $y_{112} := x_{18} x_{10} + x_{19} x_9 + x_{18} + x_9 + x_{10} + x_{23}$
 $y_{113} := x_{17} x_{10} + x_{19} x_8 + x_{17} + x_8 + x_{10} + x_{24}$
 $y_{114} := x_{17} x_9 + x_8 x_{18} + x_8 + x_9 + x_{25}$
 $y_{115} := x_4 x_{31} + x_{108} x_{30} + x_4 + x_{108} + x_{30}$
 $+ 1 + x_{31} + x_{109}$
 $y_{116} := x_3 x_{31} + x_{108} x_{29} + x_3 + x_{108} + x_{29}$
 $+ 1 + x_{31} + x_{110}$
 $y_{117} := x_3 x_{30} + x_{29} x_4 + x_3 + x_4 + x_{29} + x_{30}$
 $+ x_{111}$
 $y_{118} := x_1 x_{22} + x_2 x_{21} + x_1 + x_{21} + x_{22} + x_{105}$
 $y_{119} := x_0 x_{22} + x_2 x_{20} + x_0 + x_{20} + x_{22} + x_{106}$
 $y_{120} := x_0 x_{21} + x_{20} x_1 + x_{20} + x_{21} + x_{107}$
 $y_{121} := x_5 x_{11} + x_{12} x_6 + x_7 x_{13} + x_{11} + x_{12} + x_{13}$
 $+ x_0 x_{105} + x_1 x_{106} + x_2 x_{107} + x_{105} + x_{106}$
 $+ x_{107}$

$y_{122} := x_3 x_{109} + x_4 x_{110} + x_{108} x_{111} + x_{109}$
 $+ x_{110} + x_{111} + x_0 x_{105} + x_1 x_{106} + x_2 x_{107}$
 $+ x_{105} + x_{106} + x_{107}$
 $y_{123} := x_{29} x_{35} + x_{30} x_{36} + x_{31} x_{37} + x_{35}$
 $+ x_{36} + x_{37}$
 $y_{124} := x_{32} x_{38} + x_{33} x_{39} + x_{34} x_{40} + x_{40}$
 $y_{125} := x_0 x_{38} + x_1 x_{39} + x_2 x_{40} + x_{38} + x_{39} + x_{40}$
 $y_{126} := x_{32} x_{105} + x_{33} x_{106} + x_{34} x_{107} + x_{107}$
 $y_{127} := x_{105} x_{39} + x_{38} x_{106} + x_2 + x_{34}$
 $y_{128} := x_{105} x_{40} + x_{107} x_{38} + x_1 + x_{33}$
 $y_{129} := x_{106} x_{40} + x_{107} x_{39} + x_0 + x_{32}$
 $y_{130} := x_{17} x_{23} + x_{24} x_{18} + x_{25} x_{19} + x_{23}$
 $+ x_{24} + x_{25}$
 $y_{131} := x_{26} x_{17} + x_{18} x_{27} + x_{19} x_{28} + x_{26}$
 $+ x_{27} + x_{28}$
 $y_{132} := x_{20} x_{23} + x_{21} x_{24} + x_{22} x_{25} + x_{25}$
 $y_{133} := x_{23} x_{27} + x_{26} x_{24} + x_{19} + x_{22}$
 $y_{134} := x_{23} x_{28} + x_{25} x_{26} + x_{18} + x_{21}$
 $y_{135} := x_{24} x_{28} + x_{25} x_{27} + x_{17} + x_{20}$
 $y_{136} := x_{14} x_5 + x_6 x_{15} + x_7 x_{16} + x_{14} + x_{15} + x_{16}$
 $y_{137} := x_{11} x_8 + x_{12} x_9 + x_{10} x_{13} + x_{13}$
 $y_{138} := x_{15} x_{11} + x_{14} x_{12} + x_7 + x_{10}$
 $y_{139} := x_{11} x_{16} + x_{13} x_{14} + x_6 + x_9$
 $y_{140} := x_{12} x_{16} + x_{13} x_{15} + x_5 + x_8$
 $y_{141} := x_0 x_{26} + x_1 x_{27} + x_2 x_{28} + x_{26} + x_{27} + x_{28}$
 $y_{142} := x_{20} x_{105} + x_{21} x_{106} + x_{22} x_{107} + x_{107}$
 $y_{143} := x_{105} x_{27} + x_{26} x_{106} + x_2 + x_{22}$
 $y_{144} := x_{105} x_{28} + x_{107} x_{26} + x_1 + x_{21}$
 $y_{145} := x_{106} x_{28} + x_{107} x_{27} + x_0 + x_{20}$
 $y_{146} := x_3 x_{23} + x_4 x_{24} + x_{108} x_{25} + x_{23}$
 $+ x_{24} + x_{25}$
 $y_{147} := x_{17} x_{109} + x_{18} x_{110} + x_{19} x_{111} + x_{109}$
 $+ x_{110} + x_{111}$
 $y_{148} := x_{109} x_{24} + x_{23} x_{110} + x_{108} + x_{19}$
 $y_{149} := x_{109} x_{25} + x_{111} x_{23} + x_4 + x_{18} + 1$
 $y_{150} := x_{110} x_{25} + x_{111} x_{24} + x_3 + x_{17} + 1$
 $y_{151} := x_3 x_{35} + x_4 x_{36} + x_{108} x_{37} + x_{35}$
 $+ x_{36} + x_{37}$
 $y_{152} := x_{29} x_{109} + x_{30} x_{110} + x_{31} x_{111} + x_{109}$
 $+ x_{110} + x_{111}$
 $y_{153} := x_{109} x_{36} + x_{35} x_{110} + x_{108} + x_{31}$
 $y_{154} := x_{109} x_{37} + x_{111} x_{35} + x_4 + x_{30} + 1$
 $y_{155} := x_{110} x_{37} + x_{111} x_{36} + x_3 + x_{29} + 1$
 $y_{156} := x_{29} x_{26} + x_{30} x_{27} + x_{31} x_{28} + x_{26}$
 $+ x_{27} + x_{28}$
 $y_{157} := x_{35} x_{20} + x_{21} x_{36} + x_{22} x_{37} + x_{37}$
 $y_{158} := x_{35} x_{27} + x_{26} x_{36} + x_{31} + x_{22}$
 $y_{159} := x_{35} x_{28} + x_{37} x_{26} + x_{30} + x_{21}$
 $y_{160} := x_{36} x_{28} + x_{37} x_{27} + x_{29} + x_{20}$
 $y_{161} := x_{32} x_{11} + x_{33} x_{12} + x_{34} x_{13} + x_{13}$
 $y_{162} := x_{38} x_5 + x_{39} x_6 + x_7 x_{40} + x_{38} + x_{39} + x_{40}$
 $y_{163} := x_{38} x_{12} + x_{11} x_{39} + x_{34} + x_7$
 $y_{164} := x_{38} x_{13} + x_{40} x_{11} + x_{33} + x_6$
 $y_{165} := x_{39} x_{13} + x_{40} x_{12} + x_{32} + x_5$
 $y_{166} := x_{17} x_{14} + x_{18} x_{15} + x_{19} x_{16} + x_{14} + x_{15}$
 $+ x_{16}$
 $y_{167} := x_8 x_{23} + x_{24} x_9 + x_{25} x_{10} + x_{25}$
 $y_{168} := x_{23} x_{15} + x_{14} x_{24} + x_{19} + x_{10}$
 $y_{169} := x_{23} x_{16} + x_{25} x_{14} + x_{18} + x_9$
 $y_{170} := x_{24} x_{16} + x_{25} x_{15} + x_{17} + x_8$
 $y_{171} := x_{41} x_{54} + x_{42} x_{53} + x_{43} x_{49} + x_{44} x_{51}$
 $+ x_{111} + x_{110} + x_{109} + x_4 x_{110} + x_{108} x_{111}$
 $+ x_3 x_{109}$
 $y_{172} := x_{45} x_{55} + x_{46} x_{56} + x_{47} x_{50} + x_{48} x_{52}$
 $y_{173} := x_{45} x_{54} + x_{46} x_{53} + x_{47} x_{49} + x_{48} x_{51}$
 $y_{174} := x_{41} x_{55} + x_{42} x_{56} + x_{43} x_{50} + x_{44} x_{52}$

$y_{175} := x_{54} x_{56} + x_{53} x_{55}$
 $y_{176} := x_{54} x_{50} + x_{49} x_{55} + x_{48}$
 $y_{177} := x_{53} x_{50} + x_{49} x_{56} + x_{44}$
 $y_{178} := x_{51} x_{56} + x_{53} x_{52} + x_{43}$
 $y_{179} := x_{51} x_{50} + x_{49} x_{52} + x_{42} + x_{45}$
 $y_{180} := x_{44} x_{47} + x_{43} x_{48}$
 $y_{181} := x_{51} x_{55} + x_{54} x_{52} + x_{47}$
 $y_{182} := x_{57} x_{70} + x_{58} x_{69} + x_{59} x_{65} + x_{60} x_{67}$
 $+ x_{111} + x_{110} + x_{109} + x_4 x_{110} + x_{108} x_{111}$
 $+ x_3 x_{109}$
 $y_{183} := x_{61} x_{71} + x_{62} x_{72} + x_{63} x_{66} + x_{64} x_{68}$
 $y_{184} := x_{61} x_{70} + x_{69} x_{62} + x_{65} x_{63} + x_{64} x_{67}$
 $y_{185} := x_{57} x_{71} + x_{58} x_{72} + x_{59} x_{66} + x_{60} x_{68}$
 $y_{186} := x_{70} x_{72} + x_{69} x_{71}$
 $y_{187} := x_{70} x_{66} + x_{65} x_{71} + x_{64}$
 $y_{188} := x_{69} x_{66} + x_{65} x_{72} + x_{60}$
 $y_{189} := x_{72} x_{67} + x_{69} x_{68} + x_{59}$
 $y_{190} := x_{67} x_{66} + x_{65} x_{68} + x_{58} + x_{61}$
 $y_{191} := x_{60} x_{63} + x_{59} x_{64}$
 $y_{192} := x_{67} x_{71} + x_{70} x_{68} + x_{63}$
 $y_{193} := x_{73} x_{86} + x_{74} x_{85} + x_{75} x_{81} + x_{76} x_{83}$
 $+ x_{111} + x_{110} + x_{109} + x_4 x_{110} + x_{108} x_{111}$
 $+ x_3 x_{109}$
 $y_{194} := x_{77} x_{87} + x_{78} x_{88} + x_{79} x_{82} + x_{80} x_{84}$
 $y_{195} := x_{77} x_{86} + x_{78} x_{85} + x_{79} x_{81} + x_{80} x_{83}$
 $y_{196} := x_{73} x_{87} + x_{74} x_{88} + x_{75} x_{82} + x_{76} x_{84}$
 $y_{197} := x_{86} x_{88} + x_{85} x_{87}$
 $y_{198} := x_{86} x_{82} + x_{81} x_{87} + x_{80}$
 $y_{199} := x_{85} x_{82} + x_{81} x_{88} + x_{76}$
 $y_{200} := x_{83} x_{88} + x_{85} x_{84} + x_{75}$
 $y_{201} := x_{83} x_{82} + x_{81} x_{84} + x_{74} + x_{77}$
 $y_{202} := x_{76} x_{79} + x_{75} x_{80}$
 $y_{203} := x_{83} x_{87} + x_{86} x_{84} + x_{79}$
 $y_{204} := x_{89} x_{102} + x_{90} x_{100} + x_{91} x_{97} + x_{92} x_{99}$
 $+ x_{111} + x_{110} + x_{109} + x_4 x_{110} + x_{108} x_{111}$
 $+ x_3 x_{109}$
 $y_{205} := x_{93} x_{103} + x_{94} x_{104} + x_{95} x_{98} + x_{96} x_{101}$
 $y_{206} := x_{93} x_{102} + x_{94} x_{100} + x_{95} x_{97} + x_{96} x_{99}$
 $y_{207} := x_{89} x_{103} + x_{90} x_{104} + x_{91} x_{98} + x_{92} x_{101}$
 $y_{208} := x_{102} x_{104} + x_{100} x_{103}$
 $y_{209} := x_{102} x_{98} + x_{97} x_{103} + x_{96}$
 $y_{210} := x_{100} x_{98} + x_{97} x_{104} + x_{92}$
 $y_{211} := x_{99} x_{104} + x_{100} x_{101} + x_{91}$
 $y_{212} := x_{99} x_{98} + x_{97} x_{101} + x_{90} + x_{93}$
 $y_{213} := x_{92} x_{95} + x_{91} x_{96}$
 $y_{214} := x_{99} x_{103} + x_{102} x_{101} + x_{95}$