

Learning strikes again: the case of the DRS signature scheme

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Abstract. Lattice signature schemes generally require particular care when it comes to preventing secret information from leaking through signature transcript. For example, the Goldreich-Goldwasser-Halevi (GGH) signature scheme and the NTRUSign scheme were completely broken by the parallelepiped-learning attack of Nguyen and Regev. Several heuristic countermeasures were also shown vulnerable to similar statistical attacks. At PKC 2008, Plantard, Susilo and Win proposed a new variant of GGH, informally arguing resistance to such attacks. Based on this variant, Plantard, Sipasseuth, Dumondelle and Susilo proposed a concrete signature scheme, called DRS, that has been accepted in the round 1 of the NIST post-quantum cryptography project.

In this work, we propose yet another statistical attack and demonstrate a weakness of the DRS scheme: one can recover some partial information of the secret key from sufficiently many signatures. One difficulty is that, due to the DRS reduction algorithm, the relation between the statistical leak and the secret seems more intricate. We work around this difficulty by training a statistical model, using a few features that we designed according to a simple heuristic analysis.

While we only recover partial information on the secret key, this information is easily exploited by lattice attacks, significantly decreasing their complexity. Concretely, we claim that, provided that 100 000 signatures are available, the secret key may be recovered using BKZ-138 for first set of DRS parameters submitted to the NIST. This puts the security level of this parameter set below 80-bits (maybe even 70 bits), for an original claim of 128-bits.

Keywords: Cryptanalysis · Lattice based signature · Statistical attack · Learning · BDD

1 Introduction

At Crypto'97, Goldreich, Goldwasser and Halevi proposed the encryption and signature schemes [16] whose security relies on the hardness of lattice problems. Concurrently, a practical scheme, NTRUEncrypt was proposed, and adapted

for signatures a few years later NTRUSign [17]). In 2006, Nguyen and Regev presented a celebrated statistical attack [22] and completely broken GGH and NTRUSign in practice. The starting point of NR attack is a basic observation that any difference between signature and message always lies in the parallelepiped spanned by secret key. Thus each signature leaks partial information about the secret key, which allows to fully recover the secret key from sufficiently many signatures. In 2012, Ducas and Nguyen revisited NR attack [13] and showed that it could be generalized to defeat several heuristic countermeasures [17, 18].

Designing secure and efficient lattice based signatures remains a challenging problem. To get rid of information leaks, the now standard method is to use a delicate sampling algorithm for trapdoor inversion [15, 24].³ Following such setting, it can be proved that signatures are independent of the secret key. Yet this provable guarantee doesn't come for cheap in terms of efficiency and simplicity: it remains very tempting to make more aggressive design choices.

Such a design was proposed by Plantard, Susilo and Win [26]. It is very close from the original GGH scheme, with a modified reduction algorithm that produces signatures falling in a known hypercube, independent of the secret key. According to the authors, such property should prevent the NR attack. The main idea of [26] is to reduce vectors under ℓ_∞ -norm instead of Euclidean norm. Recently, Plantard, Sipasseuth, Dumondelle and Susilo updated this scheme, and submitted it to the NIST post-quantum cryptography project, under the name of DRS [25], standing for Diagonal-dominant Reduction Signature. Currently DRS is in the list of round 1 submissions to the NIST post-quantum cryptography project.

Our results. In this work, we present a statistical attack against the DRS scheme [26, 25]. We first notice that while the support of the transcript distribution is indeed fixed and known, the distribution itself is not, and is related to the secret key. More concretely, in the DRS signature, the reduction algorithm will introduce some correlations among coordinates w_i 's of the signature, and these correlations are strongly related to certain coefficients of the secret key \mathbf{S} .

In more details, we assume that the coefficient $\mathbf{S}_{i,j}$ can be well approximated by some function of the distribution of (w_i, w_j) and proceed to profile such a function according known instances (the training phase). Once we have the function, we can measure over sufficient signatures and obtain the guess for an unknown secret \mathbf{S} given enough signatures.

With a few extra amplification tricks, we show this attack to be rather effective: for the first set of parameters, 100 000 signatures suffice to locate all the large coefficients of the secret matrix \mathbf{S} and to determine most of their signs as well. Finally, we can feed this leaked information back into lattice attacks (BDD-uSVP attack), significantly decreasing their cost. Concretely, we claim that the

³ Alternatively, one may resort to the (trapdoorless) Fiat-Shamir with aborts approach such as done in [20, 12], yet for simplicity, we focus our discussion on the Hash-then-Sign approach.

first set of parameters offers at most 80-bits security, significantly less than the original claim of 128 bits.

As a by-product, we formalize how to accelerate BDD attack when given some known coefficients of the solution. More specifically, we are able to construct a lattice of the same volume but smaller dimension for this kind BDD instances.

Roadmap. In Sect. 2, we introduce notations and background on lattices. In Sect. 3, we provide a brief description of DRS signature scheme. Then we explain how to learn large coefficients of the secret matrix in Sect. 4, and how to combine partial information and lattice techniques to recover the full key in Sect. 5. Finally, we conclude and discuss potential countermeasure in Sect. 6.

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2 Preliminaries

We use bold lowercase letters for vectors and denote by v_i the i -th entry of the vector \mathbf{v} . We denote by $\|\mathbf{v}\|$ (resp. $\|\mathbf{v}\|_\infty$) the Euclidean norm (resp. ℓ_∞ -norm) of \mathbf{v} . For simplicity and matching programming, we assume the script of each entry of $\mathbf{v} \in \mathbb{R}^n$ is an element of $\mathbb{Z}_n = \{0, \dots, n-1\}$.

Let $\mathbf{rot}_i(\mathbf{v}) = (v_i, \dots, v_{i+n-1})$ be a rotation of $\mathbf{v} \in \mathbb{R}^n$. We denote by $\mathbf{srot}_i(\mathbf{v})$ the vector generated by $\mathbf{rot}_i(\mathbf{v})$ with each entry changing the sign independently with probability $1/2$. We define the set

$$\mathcal{T}(n, b, N_b, N_1) = \left\{ \mathbf{v} \in \mathbb{Z}^n \mid \begin{array}{l} N_b \text{ entries equal } b; \\ \mathbf{v} \text{ is a vector with exactly } N_1 \text{ entries equal } 1; \\ \text{and the rest of entries equal } 0. \end{array} \right\}.$$

We use bold capital letters for matrices and denote by \mathbf{v}_i the i -th row of the matrix \mathbf{V} , *i.e.* $\mathbf{V} = (\mathbf{v}_0, \dots, \mathbf{v}_{n-1})$. We use $\mathbf{V}_{i,j}$ to represent the entry in the i -th row and j -th column of \mathbf{V} . Let \mathbf{I}_n be the n -dimensional identity matrix. We denote by $\mathbf{ROT}(\mathbf{v})$ (resp. $\mathbf{SROT}(\mathbf{v})$) the matrix $(\mathbf{rot}_0(\mathbf{v}), \dots, \mathbf{rot}_{n-1}(\mathbf{v}))$ (resp. $(\mathbf{srot}_0(\mathbf{v}), \dots, \mathbf{srot}_{n-1}(\mathbf{v}))$). Note that all $\mathbf{srot}_i(\mathbf{v})$'s in $\mathbf{SROT}(\mathbf{v})$ are generated independently. A matrix \mathbf{V} is diagonal dominant if $\mathbf{V}_{i,i} > \sum_{j \neq i} |\mathbf{V}_{i,j}|$ for all i .

For a distribution D , we write $X \leftarrow D$ when the random variable X is sampled from D . Given a finite set S , let $U(S)$ be the uniform distribution over S . We denote by $\mathbb{E}(X)$ the expectation of random variable X .

A (full-rank) n -dimensional lattice \mathcal{L} is the set of all integer combinations of linearly independent vectors $\mathbf{b}_1, \dots, \mathbf{b}_n \in \mathbb{R}^n$, *i.e.* $\mathcal{L} = \{\sum_{i=1}^n x_i \mathbf{b}_i \mid x_i \in \mathbb{Z}\}$.

We call $\mathbf{B} = (\mathbf{b}_1, \dots, \mathbf{b}_n)$ a basis of \mathcal{L} and write $\mathcal{L} = \mathcal{L}(\mathbf{B})$. For a unimodular matrix $\mathbf{U} \in \mathbb{Z}^{n \times n}$, we have \mathbf{UB} is also a basis of $\mathcal{L}(\mathbf{B})$, *i.e.* $\mathcal{L}(\mathbf{B}) = \mathcal{L}(\mathbf{UB})$. Let $(\mathbf{b}_0^*, \dots, \mathbf{b}_{n-1}^*)$ be the Gram-Schmidt vectors of \mathbf{B} . The volume of the lattice $\mathcal{L}(\mathbf{B})$ is $\text{vol}(\mathcal{L}(\mathbf{B})) = \prod_i \|\mathbf{b}_i^*\|$ that is an invariant of the lattice. The first minimum of a lattice \mathcal{L} is $\lambda_1(\mathcal{L}) = \min_{\mathbf{v} \in \mathcal{L} \setminus \mathbf{0}} \|\mathbf{v}\|$. Given $\mathcal{L} \subseteq \mathbb{R}^n$ and $\mathbf{t} \in \mathbb{R}^n$, the distance between \mathbf{t} and \mathcal{L} is $\text{dist}(\mathbf{t}, \mathcal{L}) = \min_{\mathbf{v} \in \mathcal{L}} \|\mathbf{t} - \mathbf{v}\|$.

Lattice reduction is an important tool for solving lattice problems and estimating the security of lattice-based cryptosystems. The goal of lattice reduction is to find a basis of high quality. The quality of a basis \mathbf{B} is related to its root Hermite factor $\text{rhf}(\mathbf{B}) = \left(\frac{\|\mathbf{b}_0\|}{\text{vol}(\mathbf{B})^{1/n}} \right)^{1/n}$. Currently, the most practical lattice reduction algorithms are BKZ [27] and BKZ 2.0 [10]. We denote by BKZ- β the BKZ/BKZ 2.0 with blocksize β . In general, we assume the root Hermite factor of a BKZ- β basis is bounded by

$$\delta_\beta \approx \left(\frac{(\pi\beta)^{\frac{1}{\beta}} \beta}{2\pi e} \right)^{\frac{1}{2(\beta-1)}}$$

when $n \gg \beta > 50$.

3 The DRS Signature Scheme

In this section, we are to make a brief description of the DRS scheme. We may omit some details that are unnecessary for understanding our attack. For more details on the algorithms and implementations we refer to [25].

To start with, we introduce several public parameters of DRS:

- n : the dimension
- D : the diagonal coefficient of the secret key
- b : the magnitude of the large coefficients (*i.e.* $\{\pm b\}$) in the secret key
- N_b : the number of large coefficients per vector in the secret key
- N_1 : the number of small coefficients (*i.e.* $\{\pm 1\}$) per vector in the secret key

Following the setting provided in [25], the parameter D is chosen to be n and satisfies that $D > b \cdot N_b + N_1$.

The secret key of DRS is a matrix

$$\mathbf{S} = D \cdot \mathbf{I}_n - \mathbf{M}$$

where $\mathbf{M} = \text{SROT}(\mathbf{v})$ with $\mathbf{v} \leftarrow U(\mathcal{T}(n, b, N_b, N_1) \cap \{\mathbf{v} \in \mathbb{Z}^n \mid v_0 = 0\})$ is the noise matrix. It is easily verified that \mathbf{S} is diagonal dominant. The public key is a matrix \mathbf{P} such that $\mathcal{L}(\mathbf{P}) = \mathcal{L}(\mathbf{S})$ and the vectors in \mathbf{P} are much longer than those in \mathbf{S} .

The signature algorithm of DRS follows the one in [26] and its main component is a message reduction procedure in ℓ_∞ -norm. More specifically, the message reduction is reducing successively each large coefficient m_i of the message \mathbf{m} by

qD such that $|m_i - qD| < D$ but adding $\pm q, \pm qb$ to m_j with $j \neq i$ according to the entries of \mathbf{M} , until all coefficients of the reduced message are within $(-D, D)$. Since \mathbf{S} is diagonal dominant, the message can be reduced within bounded steps as proved in [25, 26]. Algorithm 1 illustrates a formal description of the message reduction procedure in DRS signature algorithm.

Algorithm 1: Message reduction in DRS signature algorithm

Input: a message $\mathbf{m} \in \mathbb{Z}^n$, the secret matrix \mathbf{S}
Output: a reduced message $\mathbf{w} \in \mathbb{Z}^n$ such that $\mathbf{w} - \mathbf{m} \in \mathcal{L}(\mathbf{S})$

```

1:  $\mathbf{w} \leftarrow \mathbf{m}, i \leftarrow 0, j \leftarrow 0, k \leftarrow 0$ 
2: repeat
3:    $q \leftarrow \text{int}(w_i/D)$ 
4:   if  $q \neq 0$  then
5:     for  $j = 0$  to  $n - 1$  do
6:        $w_j \leftarrow w_j - q\mathbf{S}_{i,j}$ 
7:     end for
8:      $k = 0$ 
9:   end if
10:   $k \leftarrow k + 1$ 
11:   $i \leftarrow (i + 1) \bmod n$ 
12: until  $k = n$ 
13: return  $\mathbf{w}$ 

```

Besides the reduced message \mathbf{w} , an auxiliary vector \mathbf{k} is also included in the signature and used to accelerate the verification. To verify the signature, one would first check whether $\|\mathbf{w}\|_\infty < D$ and then check whether $\mathbf{m} - \mathbf{w} = \mathbf{k}\mathbf{P}$. In later discussions, we shall ignore the auxiliary vector, because it can be calculated in polynomial time from \mathbf{w}, \mathbf{m} and the public key \mathbf{P} .

4 Learning coefficients of the secret Matrix

All DRS signatures \mathbf{w} lie in and fill the region $(-D, D)^n$. Unlike GGH scheme, the signature region is a known hypercube and independent of the secret matrix and thus DRS scheme was deemed to resist statistical attacks. However, the distribution of random signature in $(-D, D)^n$ may be still related to the secret key, which would leak some key information.

4.1 Intuition on a potential leak

Our approach is to try to recover $\mathbf{S}_{i,j}$ by studying the distribution $W_{i,j}$ of (w_i, w_j) . Indeed, when a reduction happens at index i : $\mathbf{w} \leftarrow \mathbf{w} - q\mathbf{s}_i$, and when $\mathbf{S}_{i,j} \neq 0$ some correlation is introduced between w_i and w_j . Symmetrically, correlation is also introduced when $\mathbf{S}_{j,i} \neq 0$. Another source of correlations is

created by other reductions at index $k \notin \{i, j\}$ when both $\mathbf{S}_{k,i}$ and $\mathbf{S}_{k,j}$ are non-zero; these events create much less correlations since the diagonal coefficients are much larger, but those correlations accumulate over many k 's. One is tempted to model the accumulated correlations as those of some bi-variate Gaussians with a certain covariance.

Of course, there are complicated “cascading” phenomena: by modifying a coefficient, a reduction may trigger another reduction at an other index. But let us ignore such phenomena, and just assume that several reductions at indices $k \neq i, j$ occur, followed by one reduction at index i with $q = \pm 1$, before the algorithm terminates. We depict our intuition as Figure 1.

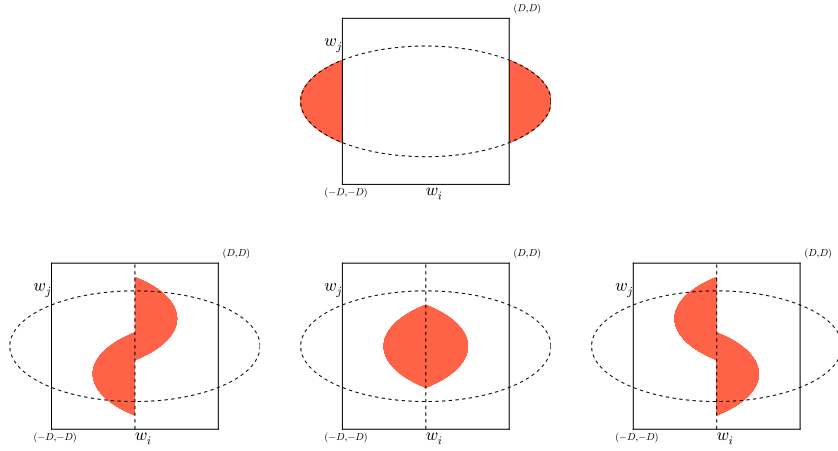


Fig. 1. Figures in the second row show the regions to which (w_i, w_j) in two cap regions will be moved by reduction at index i when $\mathbf{S}_{i,j} = -b, 0, b$ respectively from left to right.

In this simple model, we note that there are 4 degrees of liberty, 3 for the shape of the ellipsoid, and 1 for $\mathbf{S}_{i,j} = -b, 0, b$.⁴ Therefore, one may expect to be able to recover all the parameters using 4 statistical measures. One natural choice is the following. First, measure the covariance matrix of the whole distribution, which gives 3 parameters. Assuming the clipped caps have small weights, this would roughly give the shape of the ellipsoid. For the last measure, one would select only sample for which $|w_i|$ is small, so as to focus on the superimposed displaced caps. With a bit of effort one would find an appropriate measurement.

Unfortunately, it seems rather hard to determine mathematically what will precisely happen in the full reduction algorithm, and to construct by hand a

⁴ In fact, two of those degrees disappear in the exact scheme, because each row and column of \mathbf{S} has fixed euclidean length, also fixing two parameters of the ellipsoid.

measurement on the distribution of (w_i, w_j) directly giving $\mathbf{S}_{i,j}$, i.e. a function f such that $f(W_{i,j}) = \mathbf{S}_{i,j}$.

4.2 Training

While constructing such a function f by a mathematical analysis may be hard, our hope is that such function may be easy to learn using standard techniques, ranging from least-square fits to convolutional neural networks. Indeed, going back to Figure 1, recovering $\mathbf{S}_{i,j}$ from $W_{i,j}$ can essentially be viewed as a grey-scale image classification problem (the lightness of the pixel x, y corresponding to the density of $W_{i,j}$ at (x, y) .)

Features. We therefore proceed to design a few *features*, according to the intuition built above. The average of each w_i is supposed to be 0, thus we do not treat it as a feature. Certainly, the covariance information is helpful, but we also introduce extra similar statistics to allow the learning algorithm to handle extra perturbations not captured by our simple intuition. We restrict our features to be symmetric: a sample (x, y) should have the same impact than $(-x, -y)$. Indeed, while quite involved, the whole reduction process preserves this symmetry.

More specifically, by scaling a factor of D , consider the distribution W to have support $(-1, 1)$. For a function f over $(-1, 1)^2$, we write $f(W) = \mathbb{E}_{(x,y) \leftarrow W}(f(x))$. The features mentioned before are listed below⁵:

- $f_1(W) = D \cdot \mathbb{E}_{(x,y) \leftarrow W}(x \cdot y)$;
- $f_2(W) = D \cdot \mathbb{E}_{(x,y) \leftarrow W}(x \cdot |x|^{1/2} y)$;
- $f_3(W) = D \cdot \mathbb{E}_{(x,y) \leftarrow W}(x \cdot |x| \cdot y)$;

We could go on with higher degrees, but this would cause some trouble. First, higher degree moments converge much slower. Secondly, taking too many features would lead to over-fitting.

Then, following our intuition, we want to also consider features that focus on the central region. Still, we do not want to give too much weight to samples with x very close to 0. Indeed, there will be some extra perturbation after the reduction at index i , which could flip the sign of x . A natural function to take this into account is the following.

- $f_4(W) = D \cdot \mathbb{E}_{(x,y) \leftarrow W}(x(x-1)(x+1) \cdot y)$.⁶

The most contributing sample will be the one for which $x = \pm 1/\sqrt{3}$, and it is not clear that this is the optimal range to select. We therefore offer to the learning algorithm a few variants of the above that select samples with smaller values of x , hoping that it can find a good selection by combining all of them:

⁵ We introduced a re-normalization factor D in our experiments. We keep it in this paper for consistency.

⁶ As we are only going to consider linear models in our features, we could equivalently replace this feature by $\mathbb{E}_{(x,y) \leftarrow W}(x^3 \cdot y)$ because of the presence of f_1 .

- $f_5(W) = D \cdot \mathbb{E}_{(x,y) \leftarrow W}(2x(2x-1)(2x+1) \cdot y \mid |2x| \leq 1)$;
- $f_6(W) = D \cdot \mathbb{E}_{(x,y) \leftarrow W}(4x(4x-1)(4x+1) \cdot y \mid |4x| \leq 1)$;
- $f_7(W) = D \cdot \mathbb{E}_{(x,y) \leftarrow W}(8x(8x-1)(8x+1) \cdot y \mid |8x| \leq 1)$;

For any function f over \mathbb{R}^2 , we call $f^t : (x, y) \mapsto f(y, x)$ the transpose of f . So far, we have introduced 13 different features, *i.e.* f_1, \dots, f_7 and their transposes $f_8 = f_2^t, \dots, f_{13} = f_7^t$.⁷ We plot these functions in Figure 2.

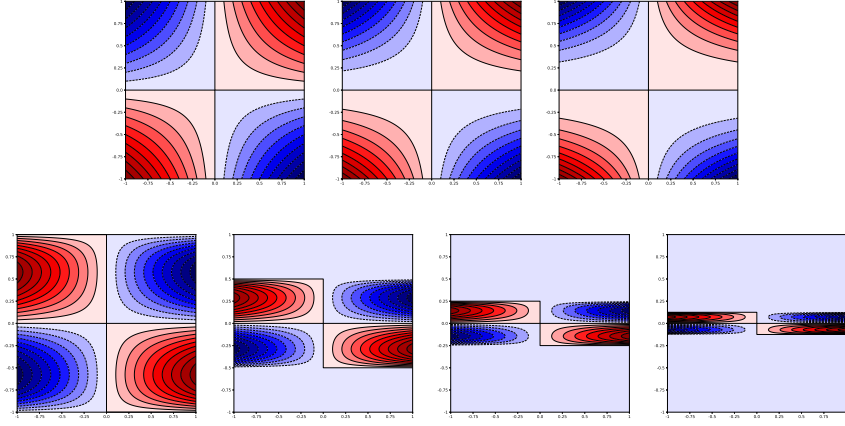


Fig. 2. The color matrices for f_1, \dots, f_7 . For any pixel at (x, y) , its color is red (full-line contour), blue (dashed-line contour) when $f_i(x, y) > 0, \leq 0$ respectively. The deeper the color is, the larger $|f_i(x, y)|$ is.

Generating data. Then, we proceed to measure each $W_{i,j}$ for known values of $\mathbf{S}_{i,j}$, say, using 400 000 samples for each key \mathbf{S} , and using 30 different keys \mathbf{S} . This is implemented by our script `gen_training.py`. This took about 38 core-hours.

Training. While we did experiment a bit with various advanced machine learning techniques (support vector regression [7], random forest regression [19] and artificial neural networks), we were unable to obtain better results than with linear models $f = \sum_{\ell=1}^{13} x_{\ell} f_{\ell}$ trained using the least-square fit method.

Evaluating and refining our model. After preliminary experiments, we noted that, depending on their position $i - j$, some coefficients $\mathbf{S}_{i,j}$ seem easier to learn than others. In this light, it is not clear that one should use the same function f for all indices i, j . Instead, we constructed two functions $f^+ = \sum x_{\ell}^+ f_{\ell}$, $f^- = \sum x_{\ell}^- f_{\ell}$ respectively for indices such that $i - j \bmod n \geq n/2$ and $i - j \bmod n < n/2$. The data generated in the last phase provided $\frac{n^2}{2}$ (resp.

⁷ Since f_1 is a symmetric function of (w_i, w_j) , we did not count its transpose.

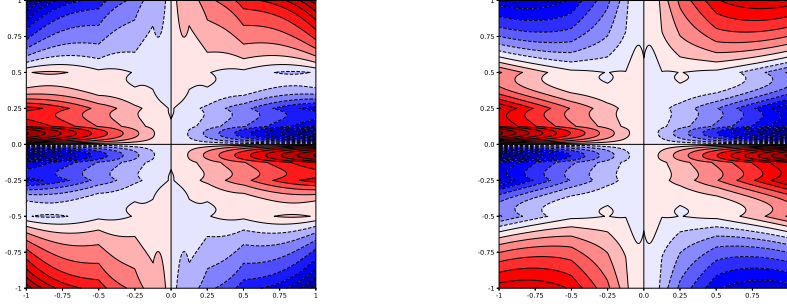


Fig. 3. The left graph is the color matrix for f^- , and the right one is for f^+ .

$\frac{n(n-2)}{2}$) interpolations for f^+ (resp. f^-), i.e. the key is the measured f_ℓ for $W_{i,j}$ and the value is the known $\mathbf{S}_{i,j}$. The model obtained by the least-square fit method is provided in Table 1 and plotted in Figure 3. Moreover, the distributions of $f^+(W_{i,j})$, $f^-(W_{i,j})$ for $\mathbf{S}_{i,j} = \pm b, \pm 1, 0$ are illustrated in Figures 4 and 5.

Remark 1. For other set of parameters, or even to refine our attack and recover more secret information, it is of course possible to cut our modeling in more than 2 pieces, but this requires more training data, and therefore more computational resources.

i	1	2	3	4	5	6	7
x_i^-	-48.3640	354.9788	-289.1598	58.7149	-3.7709	-2.9138	2.3777
i	8	9	10	11	12	13	
x_i^-	-21.2574	6.6581	3.5598	1.0255	0.4835	-0.3637	
i	1	2	3	4	5	6	7
x_i^+	-67.9781	324.8442	-248.7882	44.6268	-4.1116	-2.6163	2.8288
i	8	9	10	11	12	13	
x_i^+	-9.0923	3.1639	-0.8145	0.5204	0.3486	0.4920	

Table 1. The model trained from 30 keys and 400 000 signatures per key.

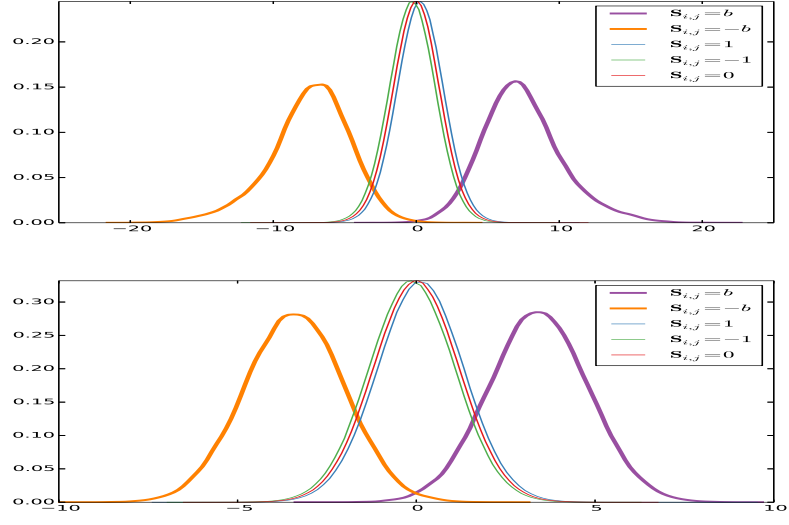


Fig. 4. The distributions of $f^-(W_{i,j})$, $f^+(W_{i,j})$ for $S_{i,j} = \pm b, \pm 1, 0$. The upper one corresponds to f^- and the lower one corresponds to f^+ . Experimental values measure over 20 instances and 400 000 samples per instance.

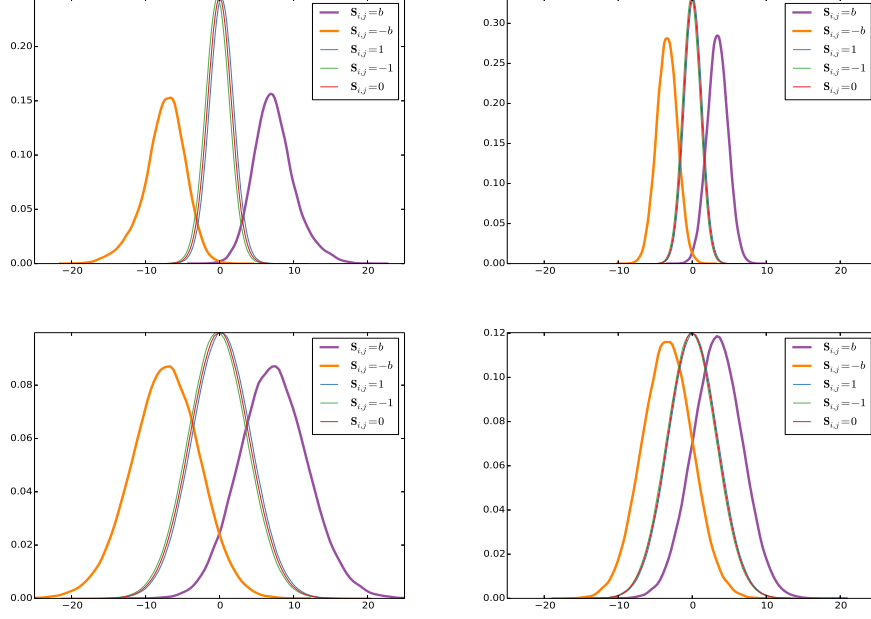


Fig. 5. The impact from sample sizes on the measured distributions of $f^-(W_{i,j})$, $f^+(W_{i,j})$. The left graphs correspond to f^- and the right graphs correspond to f^+ . The upper graphs measure over 20 instances and 400 000 samples per instance, and the lower graphs measure over 20 instances and 50 000 samples per instance.

Remark 2. As shown in Figures 4 and 5, predicted values $f(W_{i,j})$ for large coefficients are usually of larger size than those for $-1, 0, 1$. Compared with large coefficients far from the main diagonal, those near the main diagonal tend to be predicted as a number of larger size. Furthermore, as sample size growing, the variances of $f(W_{i,j})$ decrease which provides a sanity check for our models.

4.3 Learning

Following the previous method, we obtain a matrix \mathbf{S}' consisting of all guesses of $\mathbf{S}_{i,j}$'s.⁸ While clear correlations between the guess \mathbf{S}' and \mathbf{S} were observed, the guess was not good enough by itself for the number of samples that we used. In the following, we exploit the “absolute-circulant” structure of the secret key to improve our guess.

Determining the locations. Notice that all $\mathbf{S}_{i,j}$'s in a same diagonal are of the same absolute value, hence we used a simple trick to enhance the contrast be-

⁸ We ignore diagonal elements because they are public.

tween large and small coefficients. It consists in calculating

$$\mathcal{W}_k = \sum_{i=0}^{n-1} \mathbf{S}_{i, (i+k) \bmod n}^{\prime 2}$$

as the weight of the k -th diagonal. Since we used two different features for coefficients near/far from the main diagonal, for better comparison, the first $n/2 - 1$ weights were scaled by their maximum and so were the last $n/2$ weights. We denote by \mathcal{W}_k^- the first $n/2 - 1$ scaled weights and by \mathcal{W}_k^+ the last $n/2$ ones.

As illustrated in Figure 6, the scaled weights of those diagonal consisting of large coefficients are significantly larger than others. A straightforward method to locate large coefficients is to pick the N_b largest scaled weights.

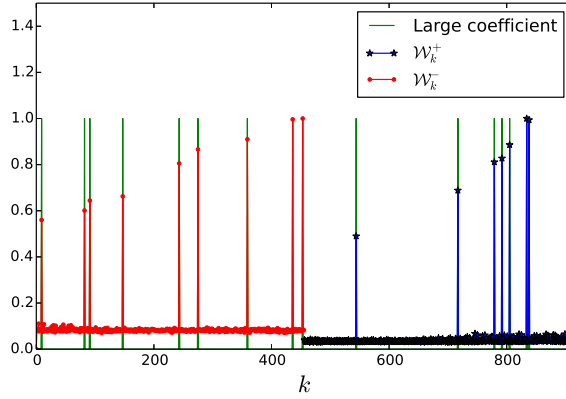


Fig. 6. Large coefficients and scaled weights. Experimental values measure over 400 000 samples.

Verified by experimental results, we were able to perfectly locate all large coefficients, provided we collected sufficient signatures. For different sample size, i.e. the number of signatures, we respectively tested 20 instances and checked the accuracy of locations for large coefficients. All experimental data is illustrated in Table 2.

#signs	13/16	14/16	15/16	16/16
50 000	5	3	6	6
100 000	-	-	-	20
200 000	-	-	-	20
400 000	-	-	-	20

Table 2. Experimental measure of location accuracy. The column, labeled by $K/16$, shows the number of tested instances in which the largest N_b scaled weights corresponded to exactly K large coefficient diagonals.

Determining the signs. We straightforward assumed the sign of measured feature $f(W_{i,j})$ is the same to that of $\mathbf{S}_{i,j}$, when $\mathbf{S}_{i,j} = \pm b$. Unlike guessing locations, we could not recover all signs of large coefficients exactly, but as the sample size grows, we were still able to get a high accuracy, denoted by p . Then, we may expect to recover all signs of large coefficients in each row exactly with a probability $p_{row} = p^{N_b}$ (in our case $N_b = 16$).

Moreover, we noticed that the accuracy of guessing signs for large coefficients in the lower triangle, i.e. $\mathbf{S}_{i,j}$ with $i > j$, is higher than that for large coefficients in the upper triangle, thus we denote by p_l and p_u the accuracy corresponding to lower and upper triangle. That may suggest us to guess the signs of large coefficients from the last row to the first row. Table 3 exhibits the experimental data for p_l, p_u, p and p_{row} .

#signs	p_l	p_u	p	p_{row}
400 000	0.9975	0.9939	0.9956	0.9323
200 000	0.9920	0.9731	0.9826	0.7546
100 000	0.9722	0.9330	0.9536	0.4675
50 000	0.9273	0.8589	0.8921	0.1608

Table 3. Experimental measures for p_l, p_u, p and p_{row} . All values measure over 20 instances.

Comparing guessing locations, guessing signs is much more sensitive to the number of signatures. That is because the sign information of $\mathbf{S}_{i,j}$ only comes from $f(W_{i,j})$ rather than all features in the same diagonal so that it requires a more precise measurement. Furthermore, we tried a modified model for guessing signs: in training phase, we mapped $\mathbf{S}_{i,j}$ to $\lfloor \mathbf{S}_{i,j}/b \rfloor$ and then find x_ℓ 's determining the global feature. Intuitively, the modified model further emphasizes large coefficients, but it performed almost the same to the current model in practice.

5 Exploiting partial Secret Key knowledge in Lattice attacks

Using the technique described in last section, we are able to recover exactly all off-diagonal large coefficients, with high probability (in addition to the diagonal coefficient D). First, we show how to adapt the BDD-uSVP attack, by exploiting the known coefficients of a row \mathbf{s}_k to decrease the distance of the BDD target to the lattice, making the problem easier. Then, we show a more involved version, where we also decrease the dimension of the lattice while maintaining its volume. While not much is gained to recover a first secret row \mathbf{s}_k , this technique makes guessing the rest of the key much faster.

In later discussion, assume that we have already successfully determined all $-b, b$ and D coefficients in \mathbf{s}_k . Let $M = \{m_0, \dots, m_{N_b}\}$ be the set of all m 's such that $\mathbf{S}_{k,m} \in \{-b, b, D\}$ where $m_0 < \dots < m_{N_b}$.

5.1 Direct BDD-uSVP attack

Let $\mathbf{t} \in \mathbb{Z}^n$ such that, if $|\mathbf{S}_{k,i}| > 1$, $t_i = \mathbf{S}_{k,i}$, otherwise $t_i = 0$, then $\text{dist}(\mathbf{t}, \mathcal{L}) = \sqrt{N_1 + 1}$. We construct a new lattice \mathcal{L}' with a basis

$$\mathbf{P}' = \begin{pmatrix} \mathbf{t} & 1 \\ \mathbf{P} & 0 \end{pmatrix} \in \mathbb{Z}^{(n+1) \times (n+1)},$$

we have $\text{vol}(\mathcal{L}') = \text{vol}(\mathcal{L}) \approx D^n$ and \mathcal{L}' contains a vector of Euclidean norm $\sqrt{N_1 + 1} \ll D$. Thus, to recover \mathbf{s}_k , it suffices to solve uSVP on \mathcal{L}' .

In [4], authors gave an estimation of the required blocksize for BKZ to solve uSVP and it has been shown to coincide with the actual behaviour of BKZ in a very recent paper [2]. Following this result, we claim that \mathbf{s}_k could be recovered by BKZ- β when β satisfies:

$$\sqrt{\frac{\beta}{n+1}} \cdot \sqrt{N_1 + 1} \leq \delta_\beta^{2\beta-n-1} \cdot D^{\frac{n}{n+1}}.$$

We conclude that running BKZ- β with $\beta = 146$ should be sufficient to break the scheme. Typically [8, 1], it is estimated that BKZ- β converges after about 16 tours, therefore making $16(n+1)$ calls to SVP- β :

$$C_{\text{BKZ-}\beta} = 16(n+1) \cdot C_{\text{SVP-}\beta}.$$

Though the factor 16 may shrink by increasing the blocksize β' progressively from 2 to β . Estimation of the cost of $C_{\text{SVP-}\beta}$ varies a bit in the literature, also depending on the algorithm used. The standard reference for estimating the cost enumeration is [10], which gives a cost of $2^{0.270\beta \ln \beta - 1.019\beta + 16.10}$ [3, 9] clock-cycles. Alternatively, the Gauss-Sieve algorithm [21] with dimension for free and other tricks showed a running time of $2^{0.396\beta + 8.4}$ clock cycles [11].

Those two methods lead respectively to estimates of 2^{78} and 2^{80} clock-cycles to recover one secret row. One could of course repeat the attack over each row, but below, we present a strategy that slightly reduce the cost of guessing a first row, and greatly reduce the cost of guess all the other rows.

Remark 3. These numbers are likely to be over-estimates. Indeed, while cost predictions have not been provided, the enumeration algorithms have been sped up in practice recently with the discrete-pruning technique [14, 5, 28]. Unfortunately, the record timing on SVP challenges up to SVP-150 are difficult to use, as they only solve SVP up to an approximation factor of 1.05, which is significantly easier than the exact SVP typically used in BKZ. Similarly, avenues for improvements are discussed in [11], such as using a faster sieve, or amortizing certain costs inside the BKZ loop. Moreover, a long-standing question remains open: could it be more efficient to use an approx-SVP oracle with a larger block-size in BKZ to achieve similar reduction faster.

5.2 BDD-uSVP attack with dimension reduction

Next we detail how to also reduce the dimension of \mathcal{L}' but maintain its volume, when exploiting known coefficients of a BDD solution.

Let $\mathbf{H} = (h_{i,j})_{i,j}$ be the HNF (Hermite Normal Form) of \mathbf{P} satisfying:

- $h_{i,i} > 0$;
- $h_{j,i} \in \mathbb{Z}_{h_{i,i}}$ for any $j > i$.
- $h_{j,i} = 0$ for any $j < i$.

Let $I = \{i \mid h_{i,i} > 1\}$. In general, $|I|$ is very small (say ≤ 5), for example $|I| = 1$ if $\det(\mathbf{H})$ is square-free. Thus we have, with a high probability, that $I \cap M = \emptyset$, i.e. $h_{m,m} = 1$ for any $m \in M$. If not so, we choose the another row $\mathbf{s}_{k'}$ of \mathbf{S} . Let $\{l_0, \dots, l_{n-2-N_b}\} = \mathbb{Z}_n \setminus M$ where $l_0 < \dots < l_{n-2-N_b}$.

Let $\mathbf{H}' = (h'_{i,j})_{i,j}$ be a matrix of size $(n - N_b - 1) \times (n - N_b - 1)$, in which $h'_{i,j} = h_{l_i, l_j}$. Let $\mathbf{a} = (a_0, \dots, a_{n-N_b-2})$ where $a_i = \sum_{m \in M} \mathbf{S}_{k,m} h_{m, l_i}$. Let \mathcal{L}' be the lattice generated by

$$\mathbf{B} = \begin{pmatrix} \mathbf{H}' \\ \mathbf{a} & 1 \end{pmatrix} \in \mathbb{Z}^{(n-N_b) \times (n-N_b)}.$$

We first have that

$$\text{vol}(\mathcal{L}') = \det(\mathbf{H}') = \frac{\det(\mathbf{H})}{\prod_{m \in M} h_{m,m}} = \det(\mathbf{H}) = \text{vol}(\mathcal{L}).$$

Secondly, we can prove that \mathcal{L}' have an unusually short vector corresponding to all small coefficients of \mathbf{s}_k . Indeed, let $\mathbf{c} \in \mathbb{Z}^n$ such that $\mathbf{c}\mathbf{H} = \mathbf{s}_k$, then $\mathbf{c}_m = \mathbf{S}_{k,m}$ for any $m \in M$ thanks to $h_{m,m} = 1$. Let $\mathbf{c}' = (c_{l_0}, \dots, c_{l_{n-2-N_b}})$, then

$$(\mathbf{c}', 1)\mathbf{B} = (\mathbf{c}'\mathbf{H}' + \mathbf{a}, 1) = (s_{l_0}, \dots, s_{l_{n-2-N_b}}, 1) := \mathbf{v}'.$$

Notice that $\|\mathbf{v}'\| = \sqrt{N_1 + 1} \ll \text{vol}(\mathcal{L}')^{\frac{1}{n-N_b}} \approx D^{\frac{n}{n-N_b}}$, we may use uSVP oracle to find \mathbf{v}' .

Using the same argument than in the previous subsection, we could recover \mathbf{v}' , namely \mathbf{s}_k , by BKZ- β when β satisfies:

$$\sqrt{\frac{\beta}{n - N_b}} \cdot \sqrt{N_1 + 1} \leq \delta_\beta^{2\beta - n + N_b} \cdot D^{\frac{n}{n - N_b}}.$$

This condition is satisfied for $\beta = 138$. Based respectively on [10] and [11], this gives attack in 2^{73} and 2^{77} clock-cycles. Again, these numbers should be taken with a grain of salt (see Remark 3).

5.3 Cheaply recovering all the other rows

Once a vector \mathbf{s}_k has been fully recovered, we have much more information on all the other secret rows. In particular, we know all the positions of the 0, and this allows to decrease the dimension from n to $N_b + N_1$.

As in previous section we are able to construct a $(N_b + N_1)$ -dimensional lattice \mathcal{L}' of the same volume as \mathcal{L} and containing a vector of length $\sqrt{N_b \cdot b^2 + N_1}$. When $(n, D, b, N_b, N_1) = (912, 912, 28, 16, 432)$, using BKZ-50 is enough⁹ to recover the target vector and the cost is negligible compared to the cost of the first step.

6 Conclusion

We have shown that the DRS scheme is in principle susceptible to a statistical attack: signatures do leak information about the secret key. More concretely, for the first set of parameters submitted to the NIST [25], we have shown its security should be considered below 80-bits after $100\,000 \approx 2^{17}$ signatures have been released, contradicting the original claim of 128-bits of security. While such a large number of signature may not be released in many applications, it remains much lower than the bound of 2^{64} signatures given by the NIST call for proposal [23, Sec 4.A.4].

We also warn the reader that for demonstrating the principle of our attack, we have only focused on the easiest secret coefficients. But from Figure 4, it seems also possible to deduce more information on the key. We strongly suspect that, focusing on the very near-diagonal coefficients, it could be possible to get the locations of a few 0's and ± 1 's as well, using more signatures, a more focused statistical model, and the diagonal amplification trick. This may lead to a full break in practice of this parameter set. Moreover, our estimates do not take account of the recent discrete pruning technique for enumeration [14, 5, 28], that has unfortunately not yet been the object of easily usable predictions.

In addition, we would like to clarify our views on lattice-based crypto security estimates. While we did stick to the best known attack methodology in this paper so as to not overclaim our cryptanalytic result, we do not recommend this approach for design and security claims, considering that the state of the art in lattice reduction is still making significant progress [14, 5, 28, 11].

6.1 Viability of the DRS design, and potential countermeasure.

We note nevertheless that this statistical attack seems much less powerful than the statistical attacks presented in [22, 13] against the original schemes GGH [16]

⁹ The required blocksize can be much smaller, but we should use a different estimation for δ_β for small β [10, 29].

and NTRUSign [17]. Indeed, our attack requires much more signatures, and still only recovers partial secret key information. In this light, we *do not* conclude that the approach of [25] is to be discarded at once, at least if it shows competitive performances. We therefore suggest several directions to improve the security of the scheme.

Disclaimer. These suggestions should however not be understood as a pledge for the DRS scheme [25]: we believe a much more thorough analysis of the leak should be provided, and that a statistical argument would be much more reassuring than the experimental failure of the type of attack described in this paper.

Randomization. In [26, 25], it is suggested that the orders of the indices j for the reductions $\mathbf{w} \leftarrow q\mathbf{s}_j$ could be randomized. This modification does not affect the intuition developed in Section 4.1. We suspect it might make the attack somewhat simpler. Indeed, in the current deterministic version, the coefficients far from the diagonal seemed harder to learn, forcing us to use two different models f^- and f^+ . We believe that this complication could be removed against the randomized variant.

Set of secret coefficients. Rather than a sparse yet wide set $\{0, \pm 1, \pm b\}$ for the coefficients of \mathbf{S} , we recommend an interval of integers $\{-u, \dots, u\}$, where u is chosen such that the Euclidean length of the rows is maintained (say, on average). As we saw (Figures 4), larger coefficients are easier to detect, and the gap between 1 and b allows one to make a guess with much more confidence. Note that this does only mitigate the attack, but would not seal the leak.

Structure of the secret matrix. Secondly, the “absolute-circulant” structure could be removed without affecting the size of the secret key; indeed, the whole matrix, could be streamed by a PRG, only keeping the seed as the new secret key.¹⁰ Again, this only mitigates the attack, but would not seal the leak.

Perturbation/drowning. Depending on the situation, adding well-designed perturbation may [24] or may not [17, 13] be an effective countermeasure against statistical attacks. Given the track record of heuristic countermeasures, we find the formal approach preferable. Drowning is a similar idea in spirit, but the added noise has a fixed distribution, typically much larger than what is to be hidden.

We note that the problem of directly trying to forge a signature seems harder than recovering the secret key with the current parameters of DRS [25]. This means that allowing larger vectors for signatures (up to a certain cross-over point) should not affect security. This gives a lot of room for perturbation or drowning, for which ad-hoc concrete statistical statements could plausibly be made, maybe exploiting Renyi divergence as in [4, 6].

¹⁰ Variants can be designed so that each row can be generated on demand.

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